



A general framework for stochastic traveling waves, with application to neural field equations.

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# Outline

- ▶ Motivation: neural field equations
- ▶ Stochastic Differential Equations
- ▶ Tracking the Wavefront
- ▶ Short-time stability
- ▶ Long-time behaviour

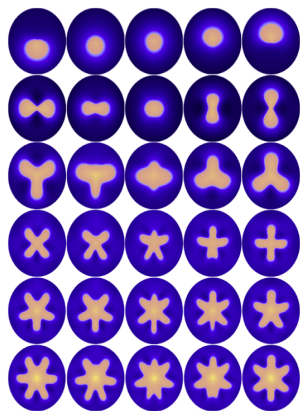
## Motivation: neural field equations (I)

Spatio-temporal model for activity states in physical cortical slice

$$\partial_t u_t(x) = -u_t(x) + \int_{\mathbb{R}} w(x-y)F(u_t(y))dy, \quad x \in \mathbb{R}.$$

- ▶  $u_t(x)$  is the activity of a typical neuron at position  $x$  in the cortical region modeled as  $\mathbb{R}$
- ▶  $w \in L^1(\mathbb{R})$  represents the spatial distribution of neuronal synaptic connections
- ▶  $F$  is the nonlinear gain function, typically taken to be a sigmoid

## Neural field equations (II)



- ▶ Much studied in mathematical neuroscience literature
- ▶ Good models for describing signal propagation in cortical slices
- ▶ Propagation of activity in the brain important in characterizing neural disorders (e.g. epilepsy) as well as normal functionality
- ▶ Have been used to make a number of experimentally verified predictions

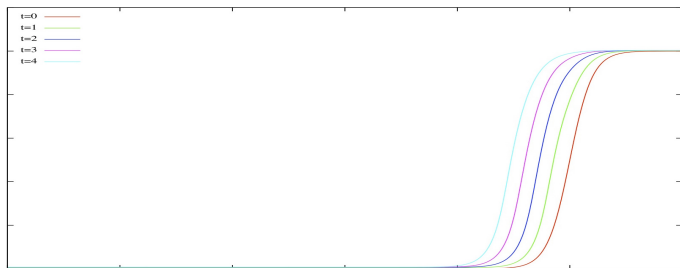
From Folias and Bressloff, Phys. Rev. Lett., 95, 2005

## Motivation: neural field equations (III)

Main interest is the existence of **traveling front** solutions:  
 $u_t(x) = \varphi_0(x - ct)$ ,  $c \in \mathbb{R}$ . Substituting into NF equation

$$0 = A\varphi_0 + f(\varphi_0), \quad (*)$$

where  $A\varphi_0 := c\varphi_0' - \varphi_0$  and  $f(\varphi_0) := w * F(\varphi_0)$ .



By translation invariance,  $(\varphi_\alpha)_{\alpha \in \mathbb{R}}$  where  $\varphi_\alpha = \varphi_0(\cdot + \alpha)$  is a family of solutions to (\*).

## Motivation: traveling pulses

A variation of the NF equation is

$$\begin{cases} \partial_t u_t = -u_t + w * F(u_t) - v_t \\ \partial_t v_t = \theta u_t - \epsilon v_t. \end{cases}$$

Can this time find a solution of the form  $(\hat{u}(\cdot - ct), \hat{v}(\cdot - ct))$  such that  $\varphi_0 = (\hat{u}, \hat{v}) \in [L^2(\mathbb{R})]^2$ . By substitution,  $\varphi_\alpha = \varphi_0(\cdot + \alpha)$  solves

$$0 = A\varphi_\alpha + f(\varphi_\alpha), \quad \alpha \in \mathbb{R},$$

$$\text{where } A\varphi_\alpha = c\varphi'_\alpha + \begin{pmatrix} -1 & -1 \\ \theta & -\epsilon \end{pmatrix} \varphi_\alpha, \quad f(\varphi_\alpha) = \begin{pmatrix} w * F(\hat{u}) \\ 0 \end{pmatrix}.$$

Since  $\hat{u} \in L^2(\mathbb{R})$ , the solution is a **traveling pulse**, rather than a front.

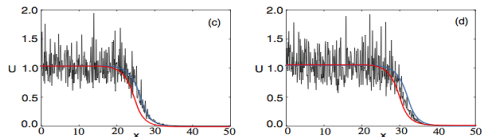
# Motivation: stochastic neural field equations

Stochastic version on NF equation

$$du_t = [-u_t + w * F(u_t)] dt + dW_t^Q$$

where  $(W_t^Q)_{t \geq 0}$  is  $L^2(\mathbb{R})$ -valued  $Q$ -Wiener process

- ▶ Studied in [Bressloff and Webber, 2012], [Kilpatrick and Ermentrout, 2013], and [Kruger and Stannat, 2014].
- ▶ Main idea: Decompose  $u_t(x) = \varphi_0(x - ct - C(t)) + v_t(x)$  and try to choose  $C(t)$  in a sensible way.



From Folias and Bressloff, SIAM J. Appl. Dyn. Syst., 11, 2012

## General setting

$E_0$  be a Banach space,  $A$  and  $f$  linear and nonlinear operators respectively acting in  $E_0$ . Suppose that  $\exists (\varphi_\alpha)_{\alpha \in \mathbb{R}} \subset E_0$  such that

$$0 = A\varphi_\alpha + f(\varphi_\alpha), \quad \alpha \in \mathbb{R}.$$

Let  $H = [L^2(\mathbb{R}^d)]^N$  for  $N, d \geq 1$ , with standard i.p.  $\langle \cdot, \cdot \rangle$ . Let  $E := \varphi_0 + H$ , with topology inherited from  $H$ .

Assumptions on  $f$  and  $A$ :

- (i)  $f$  is globally Lipschitz and  $f'(u) \in L(H, H)$ .
- (ii) The operator  $A$  also acts in  $H$  and is the generator of a  $\mathcal{C}_0$ -semigroup on  $H$ .



## General setting (2)

### Assumptions on $(\varphi_\alpha)$ :

- (i) The derivatives (w.r.t norm in  $H$ )  $[d^k/d\alpha^k]\varphi_\alpha \in H$  for  $k \in \{1, 2, 3\}$ . We will denote these derivatives by  $\varphi'_\alpha$ ,  $\varphi''_\alpha$ , and  $\varphi'''_\alpha$  respectively.
- (ii)  $\|\varphi'_\alpha\|$ ,  $\|\varphi''_\alpha\|$ , and  $\|\varphi'''_\alpha\|$  are independent of  $\alpha$ .
- (iii)  $\alpha \mapsto \varphi'_\alpha$ ,  $\varphi''_\alpha$ , and  $\varphi'''_\alpha$  are all globally Lipschitz.
- (iv) Some other technical assumptions satisfied by both waves and pulses.

## General setting (3)

Consider the stochastic evolution equation

$$du_t = [Au_t + f(u_t)]dt + \varepsilon B(t)dW_t^Q, \quad (1)$$

where  $\varepsilon > 0$  and

Assumptions on the noise:

- (i)  $(W_t^Q)_{t \geq 0}$  is an  $H$ -valued  $Q$ -Wiener process with  $Q$  a bounded, symmetric, non-negative definite linear operator on  $H$  such that  $\text{Tr}(Q) < \infty$
- (ii)  $B : [0, \infty) \rightarrow L(H, H)$  is continuous, and  $\|B(t)\|_{L(H, H)} \leq C \forall t \geq 0$ .
- (iii)  $B(t)^* B(t) = \text{Id}$  for all  $t \geq 0$ .

### Proposition: existence and uniqueness

Suppose  $u_0$  is such that  $v_0^\alpha := u_0 - \varphi_0 \in H$ . Then (1) has a unique solution  $u_t = \varphi_0 + v_t^0$  where  $(v_t^0)_{t \geq 0}$  is the unique weak (and mild)  $H$ -valued solution to

$$dv_t^0 = [Av_t^0 + f(\varphi_0 + v_t^0) - f(\varphi_0)]dt + \varepsilon B(t)dW_t^Q, \quad t \geq 0.$$

## Tracking the wave

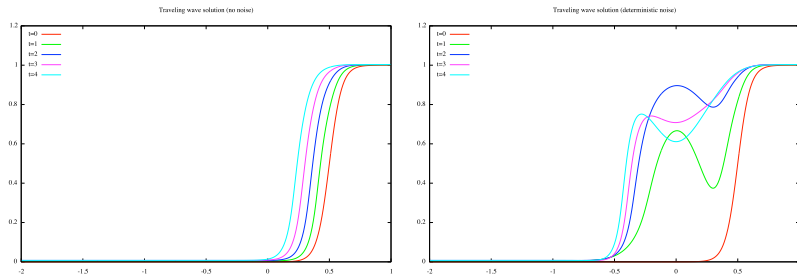
- ▶  $\exists$  ! solution  $(u_t)_{t \geq 0} \subset E$ :  $u_t = \varphi_0 + v_t^0$  where  $(v_t^0)_{t \geq 0} \subset H$
- ▶ Question: How does the noise shift the wave front?
- ▶ Decompose solution as

$$u_t = \varphi_{\beta_t} + z_t, \quad t \geq 0.$$

→ Would like to choose  $\beta_t$  to minimize  $\alpha \mapsto \|u_t - \varphi_\alpha\|^2$ .

- ▶ Can show that there always exists global minimizer, **but may not be unique and may jump!** Plus there may exist many local minima...

# Tracking the front: illustration

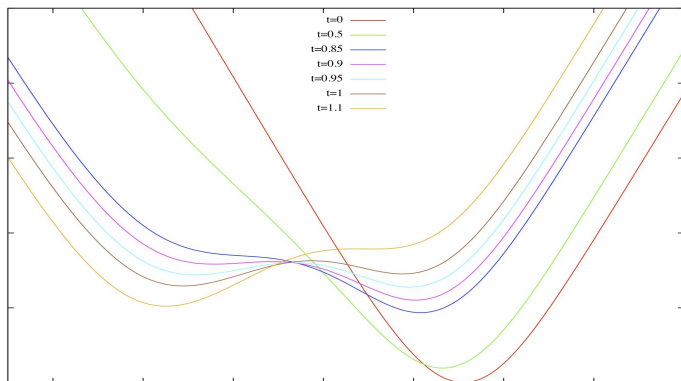


N.B. approximation is actually with 'deterministic noise' i.e.  $(u_t)_{t \geq 0}$  solves

$$\partial_t u_t = -u_t + w * F(u_t) dt + \cos(t) e^{-10x^2}$$

## Tracking the front: illustration

Numerical approximation of  $\alpha \mapsto m(t, \alpha) := \|u_t - \varphi_\alpha\|^2$  in neural field case at different times:



N.B. approximation is actually with 'deterministic noise' i.e.  $(u_t)_{t \geq 0}$  solves

$$\partial_t u_t = -u_t + w * F(u_t) dt + \cos(t) e^{-10x^2}$$

## Local dynamics of the minimum (1)

We want an SDE for the evolution of a local minimum  $\beta_t$ , i.e.

$$\Delta(u_t, \beta_t) := \frac{1}{2} \frac{d}{d\beta_t} \|u_t - \varphi_{\beta_t}\|^2 = \langle u_t - \varphi_{\beta_t}, \varphi'_{\beta_t} \rangle = 0. \quad (2)$$

Note that  $\langle u_t, \varphi'_{\beta_t} \rangle = \langle \varphi_0 + v_t^0, \varphi'_{\beta_t} \rangle = \langle \varphi_0, \varphi'_{\beta_t} \rangle + \langle v_t^0, \varphi'_{\beta_t} \rangle$ .

Guess that  $d\beta_t = \mu(t, \beta_t, u_t)dt + g(t, \beta_t, u_t)dW_t^Q$  (with  $g \in L(H, H)$ ).  
Applying Ito's Lemma to (2) we see that (formally)

$$\begin{aligned} d\Delta(u_t, \beta_t) &= \frac{\partial \Delta}{\partial u_t} B(t) dW_t^Q + \frac{\partial \Delta}{\partial \beta_t} g(t, \beta_t, u_t) dW_t^Q + \text{t.o.b.v} \\ &= \langle \varphi'_{\beta_t}, B(t) dW_t^Q \rangle + \langle u_t, \varphi'' \rangle g(t, \beta_t, u_t) dW_t^Q + \text{t.o.b.v} \end{aligned}$$

Hence  $g \cdot W = \frac{1}{\gamma(u_t, \beta_t)} \langle \varphi'_{\beta_t}, B(t)W \rangle$ , where

$$\gamma(u_t, \beta_t) = -\langle u_t, \varphi''_{\beta_t} \rangle = \frac{1}{2} \frac{d^2}{d\beta_t^2} \|u_t - \varphi_{\beta_t}\|^2.$$

## Local dynamics of the minimum (2)

SDE for dynamics of local minimum of  $\alpha \mapsto m(u_t, \alpha) := \|u_t - \varphi_\alpha\|^2$ :

$$d\beta_t = \mu(t, \beta_t, u_t)dt + \frac{1}{\gamma(u_t, \beta_t)} \langle \varphi_{\beta_t}, B(t)dW_t^Q \rangle, \quad t \geq 0.$$

Here

$$\begin{aligned} \mu(t, x, u_t) = & \frac{1}{\gamma(u_t, \beta_t)} \langle u_t, A^* \varphi'_x \rangle - \langle \varphi_0, \varphi'_0 \rangle + \\ & \frac{1}{\gamma^2(u_t, \beta_t)} \varepsilon^2 \langle B(t)QB^*(t) \varphi'_x, \varphi''_x \rangle + \\ & \frac{1}{\gamma^3(u_t, \beta_t)} \frac{\varepsilon^2}{2} \langle u_t - \varphi_x, \varphi'''_x \rangle \langle B(t)QB^*(t) \varphi'_x, \varphi'_x \rangle. \end{aligned}$$

## Local Existence and Uniqueness for $\beta_t$

**Thm:** If  $\frac{d}{d\beta_0} m(u_0, \beta_0) = 0$ , then there exists a unique solution  $\beta_t$  to the previous SDE, for all times  $t < \tau_\infty$ . Here

$$\tau_\infty = \inf\{t > 0 : \gamma(\beta_t, u_t) = 0\}.$$

The solution satisfies

$$\frac{1}{2} \frac{d}{d\beta_t} m(u_t, \beta_t) = \langle u_t - \varphi_{\beta_t}, \varphi'_{\beta_t} \rangle = 0.$$

Under some technical assumptions,  $\mathbb{P}(\lim_{t \rightarrow \tau_\infty} \beta_t \text{ exists}) = 1$ .



## Comparison to Previous Work

[Bressloff and Webber, 2012],[Kilpatrick and Ermentrout, 2013] Write  $u_t = \varphi_0 + v_t^0$ . Formally  $|\beta_t|, \|v_t^0\| \simeq \mathcal{O}(\varepsilon)$ ,  $\beta_0 = 0$ .

$$\gamma(\beta_s, u_s) = \langle \varphi'_0, \varphi'_{\beta_t} \rangle - \langle v_t^0, \varphi''_{\beta_t} \rangle \simeq \|\varphi'_0\|^2.$$

$$\beta_t \simeq \int_0^t \frac{\langle \mathcal{L}_0 v_s^0, \varphi'_0 \rangle}{\|\varphi'_0\|^2} ds + \varepsilon \int_0^t \frac{\langle \varphi'_0, B(s) dW_s^Q \rangle}{\|\varphi'_0\|^2} + \mathcal{O}(\varepsilon^2).$$

Here  $\mathcal{L}_0 = A + f'(\varphi_0)$ . Their equation is similar, with  $\varphi'_0$  replaced with  $\Psi_0$ , where  $\mathcal{L}_0^* \Psi_0 = 0$ .

[Kruger and Stannat, 2013] Recall that  $\Delta(u_t, \beta_t) = \frac{1}{2} \frac{d\|u_t - \varphi_{\beta_t}\|^2}{d\beta_t}$ . They define  $\beta_t$  to satisfy the ODE, for some  $M > 0$

$$\frac{d\beta_t}{dt} = -M\Delta(u_t, \beta_t).$$

# Local stability

Behavior of  $\|z_t\|^2 = \|u_t - \varphi_{\beta_t}\|^2$  and  $\tau_\infty$  for small  $\varepsilon$

**Spectral gap assumpt:** Suppose  $\mathcal{L}_\alpha := A + f'(\varphi_\alpha)$  has a spectral gap  $b > 0$  independent of  $\alpha$ .

**Thm:**  $\exists C$  such that for any  $t \in [0, \tau_\infty)$

$$d\|z_t\|^2 \leq (-b\|z_t\|^2 + C\|z_t\|^3)dt + \varepsilon^2 \left[ \text{Tr}(Q) - \frac{\|Q^{\frac{1}{2}}\varphi'_{\beta_t}\|^2}{\gamma(\beta_t, u_t)} \right] dt + 2\varepsilon \langle z_t, B(t)dW_t^Q \rangle.$$

**Cor:** If  $\|z_0\|^2 + \varepsilon^{\frac{1}{2}} + 2b^{-1}\varepsilon^2\text{Tr}(Q) < K$ , ( $K > 0$ , independent of  $\varepsilon$ ) then

$$\|z_t\|^2 \leq e^{-bt}(\|z_0\|^2 + \sqrt{\varepsilon}) + \varepsilon^2 C(1 - e^{-bt}),$$

for all  $t < \rho_\varepsilon$ , where

$$\rho_\varepsilon := \inf \left\{ t > 0 : 2 \int_0^t e^{br/2} \langle z_r, B(r)dW_r^Q \rangle \geq \varepsilon^{-\frac{1}{2}} \right\}.$$

# Motivation to Study the Long-Time Behaviour beyond $\tau_\infty$

Behavior of  $\|z_t\|^2 = \|u_t - \varphi_{\beta_t}\|^2$  for large  $t$ , fixed  $\varepsilon$ ?

Consider traveling wave solution to the deterministic equation

$$du_t = [Au_t + f(u_t)]dt.$$

Under some technical assumptions, [Chen,97] showed that there  $\exists \kappa > 0$  and  $\alpha, \mathcal{K} \in \mathbb{R}$  (depending on  $u_0$ ) such that

$$\|u_t - \varphi_\alpha\|_\infty \leq \mathcal{K} \exp(-\kappa t).$$

Compare this to the 1-dimensional Ornstein-Uhlenbeck Process:

$$dy_t = -\kappa y_t dt + dW_t.$$

## Reminder: the stochastic neural field equation

$$du_t = \left[ c \frac{d}{dx} u_t - u_t + w * F(u_t) \right] dt + B(t) dW_t^Q$$

This is in the moving frame!!

If the noise is stationary, then we need  $B(t) \cdot v(x) := v(x + ct)$ .

## Long time behaviour (neural field model)

Let  $\beta_t^*$  be a global minimum of  $\alpha \mapsto m(t, \alpha) := \|u_t - \varphi_\alpha\|^2$ . Let  $z_t^* = u_t - \varphi_{\beta_t^*}$ .

**Thm: (In Progress)** Subject to some technical assumptions on the noise, at any time  $t$ , almost surely  $\beta_t^*$  is the unique global minimum. Furthermore for all  $r, s \in \mathbb{R}$ ,  $r < s$

$$\begin{aligned} \|z_s^*\|^2 - \|z_r^*\|^2 &= \int_r^s \left( -2 \|z_t^*\|^2 + 2 \langle f(\varphi_{\beta_t^*} + z_t^*) - f(\varphi_{\beta_t^*}), z_t^* \rangle \right. \\ &\quad \left. + \varepsilon^2 \left[ \text{Tr}(Q) - \frac{\|Q^{\frac{1}{2}} \varphi'_{\beta_t^*}\|^2}{\gamma(\beta_t^*, v_t^0)} \right] \right) dt + 2\varepsilon \int_r^s \langle z_t^*, B(t) dW_t^Q \rangle. \end{aligned}$$

We believe that a sufficient condition on the noise should be  $\langle v, Q_t v \rangle > 0$ , for all  $v \in H$ , where

$$Q_t := \int_0^t B(s)^* Q B(s) ds.$$

## Proof Sketch

*Define the set  $E_\delta$ :* For  $\delta \in (0, 1)$  define  $E_\delta \subset E$  by  $u \in E_\delta \Leftrightarrow$

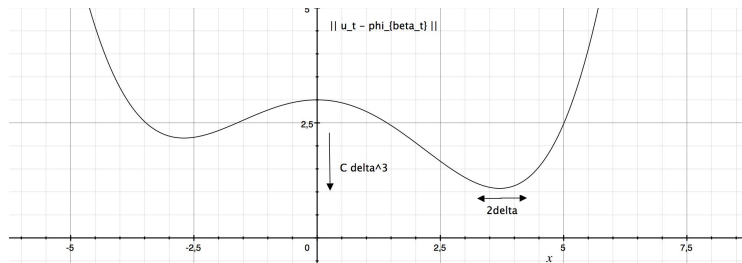
- ▶  $\|u\| \leq \delta^{-1}$
- ▶  $\exists$  a unique global minimum  $\Gamma(u)$  of  $\alpha \mapsto \|u - \varphi_\alpha\|^2$ ,
- ▶ for all  $\alpha \in [\Gamma(u) - \delta, \Gamma(u) + \delta]$ ,  $\gamma(\alpha, u) > \delta$ ,
- ▶ for all  $\alpha \in \mathbb{R} \setminus [\Gamma(u) - \delta, \Gamma(u) + \delta]$ , for some  $C > 0$ ,

$$\|u - \varphi_\alpha\| > \|u - \phi_{\Gamma(u)}\| + C\delta^3.$$

For some  $\delta \in (0, 1)$ , define the stopping times

$$\begin{aligned}\tau^{2k+1} &= \inf \left\{ t \geq \tau^{2k} : u_t \notin E_{\delta/2}, \right\}, \\ \tau^{2k+2} &= \inf \left\{ t \geq \tau^{2k+1} : u_t \in E_\delta. \right\}.\end{aligned}$$

# Minima of $\|u_t - \varphi_{\beta_t}\|$



Over the time intervals  $[\tau^{2k}, \tau^{2k+1}]$ , the SDE for  $\beta_t$  is well-defined (since  $\gamma$  has a positive lower bound). We find (using similar methods)

$$\begin{aligned} & \left\| z_{\tau^{2k+1}}^* \right\|^2 - \left\| z_{\tau^{2k}}^* \right\|^2 \\ &= \int_{\tau^{2k}}^{\tau^{2k+1}} \left( -2 \|z_t^*\|^2 + 2 \langle f(\varphi_{\beta_t^*} + z_t^*) - f(\varphi_{\beta_t^*}), z_t^* \rangle \right. \\ & \left. + \varepsilon^2 \left[ \text{Tr}(Q) - \frac{\|Q^{\frac{1}{2}} \varphi'_{\beta_t^*}\|^2}{\gamma(\beta_t^*, v_t^0)} \right] \right) dt + 2\varepsilon \int_{\tau^{2k}}^{\tau^{2k+1}} \langle z_t^*, B(t) dW_t^Q \rangle. \end{aligned}$$

The basic idea is to find conditions such that  $\tau^{2k+2} - \tau^{2k+1} \rightarrow 0$  almost surely.



## Summary

- ▶ Proved that the local minimum of  $\beta_t \rightarrow \|u_t - \varphi_{\beta_t}\|^2$  obeys an SDE over domains where the curvature  $\gamma(u_t, \beta_t)$  is nonzero.
- ▶ Proved that the stopping time  $\tau_\infty \rightarrow \infty$  as  $\epsilon \rightarrow 0$
- ▶ Obtained a bound of the form, before a stopping time  $\rho_\epsilon$  which  $\rightarrow \infty$  as  $\epsilon \rightarrow 0$ .

$$\|z_t\|^2 \leq e^{-bt}(\|z_0\|^2 + \sqrt{\epsilon}) + \epsilon^2 C(1 - e^{-bt}),$$

- ▶ (In progress) For any two times  $r, s, > 0$ ,  $r < s$ , we have the inequality

$$\begin{aligned} \|z_s^*\|^2 - \|z_r^*\|^2 &= \int_r^s \left( -2\|z_t^*\|^2 + 2\langle f(\varphi_{\beta_t^*} + z_t^*) - f(\varphi_{\beta_t^*}), z_t^* \rangle \right. \\ &\quad \left. + \epsilon^2 \left[ \text{Tr}(Q) - \frac{\|Q^{\frac{1}{2}} \varphi'_{\beta_t^*}\|^2}{\gamma(\beta_t^*, v_t^0)} \right] \right) dt + 2\epsilon \int_r^s \langle z_t^*, B(t) dW_t^Q \rangle. \end{aligned}$$

## Further Work

- ▶ Use a weighted inner product  $\langle \cdot, \cdot \rangle_\alpha$  that shifts with  $\varphi_\alpha$ .
- ▶ More investigation of the spectra / internal dynamics.
- ▶ Extend to systems with multiple degrees of freedom (such as spiral waves).
- ▶ Extend to systems where  $\varphi_\alpha$  is periodic in  $\alpha$ . (e.g. Zebra Stripes)

# Acknowledgments

This is joint work with James Inglis (INRIA Sophia-Antipolis, France).

We thank P. Bressloff, W. Stannat, E. Lang and J. Kruger for interesting and helpful discussions.

We recommend that you look at the posters of E. Lang and J. Kruger!!